# Sector150 HD

# FPV Racing Drone

# Manual

# Contents



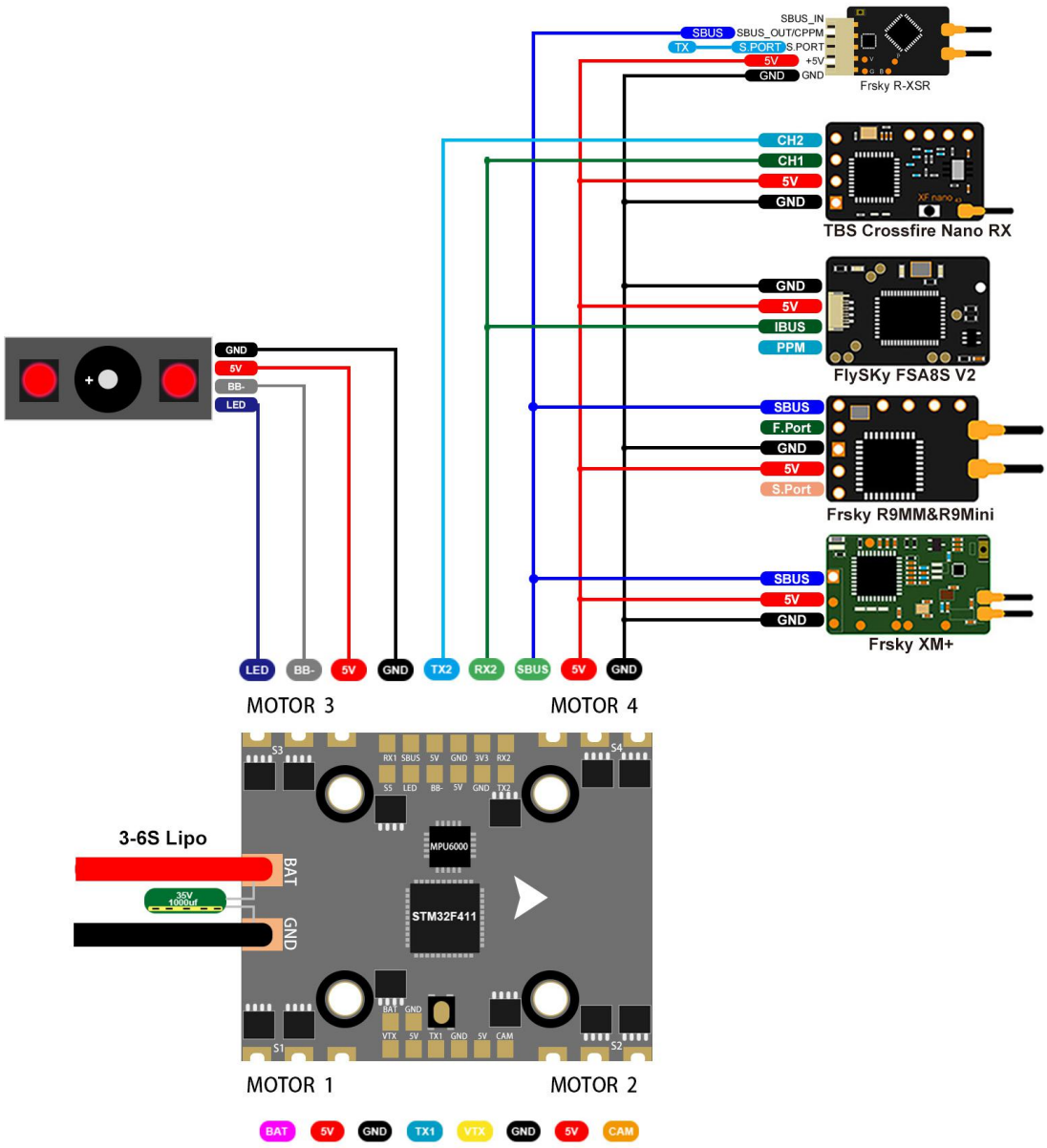
## Package IncIuded

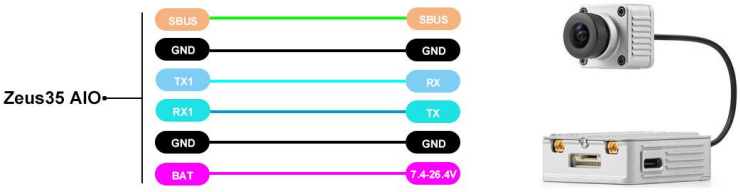
| | |
|---|---|
| Sector150 HD FPV Racing Drone *1 | Accessory Bag*1 |

# 1.Product Specifications

| Product parameters | |
|---|---|
| Model | Sector150 HD<br>FPV Racing Drone |
| Weight | 245.9g |
| Frame Kit | Sector150 Freestyle Frame Kit |
| Flight Controller | Zeus35 AIO Flight Controller |
| ESC | 35A 4in1 ESC |
| VTX | DJI Air Unit |
| Motor | 1408 kv3600 |
| Support receiver | SBUS .DSMX.i.BUS |
| Input Voltage | 3-4S Lipo |

# 2.Interface Description



# 3.Check the flight control drive

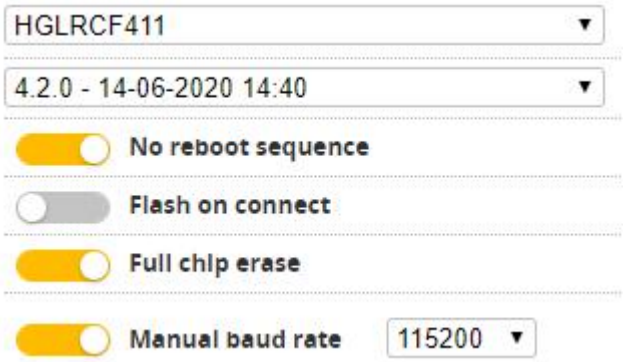
1. Long Press BOOT buttons.connect USB.The system automatically install the driver


2.Driver cannot be installed, please download ImpulseRC_Driver_Fixer


3.Double-click on the run(Plug in the flight controller to automatically install the driver)

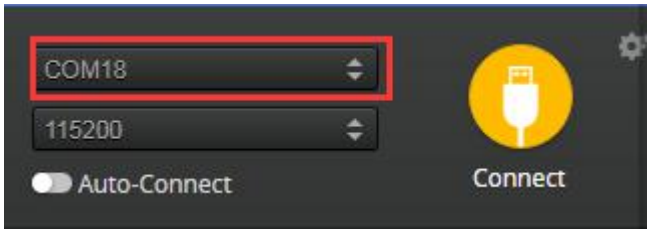

4.open betaflight configurator , enter DFU mode

5. Click Firmware Flasher Select firmware version




6.Click Load Firmware [Online] Load firmware. Flash Firmware Waiting for completion Erasing ... It will be prompted upon completion. Programming: SUCCESSFUL

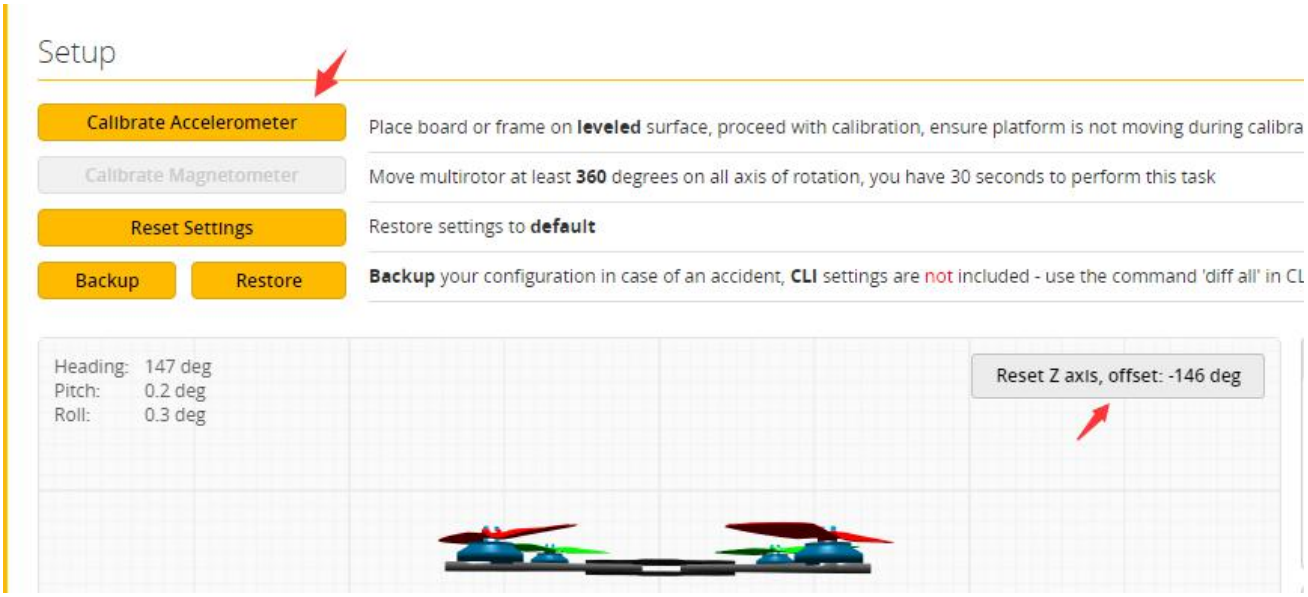
7.open betaflight configurator BETAFLIGHT 。Controller plugged into the computer. Betaflight Automatically assigned port，click “Connect” Enter setup interface（Different computer COM）



# 4.Calibration accelerometer

1. Put the aircraft horizontal and click “Reset Z axis”

Click again 

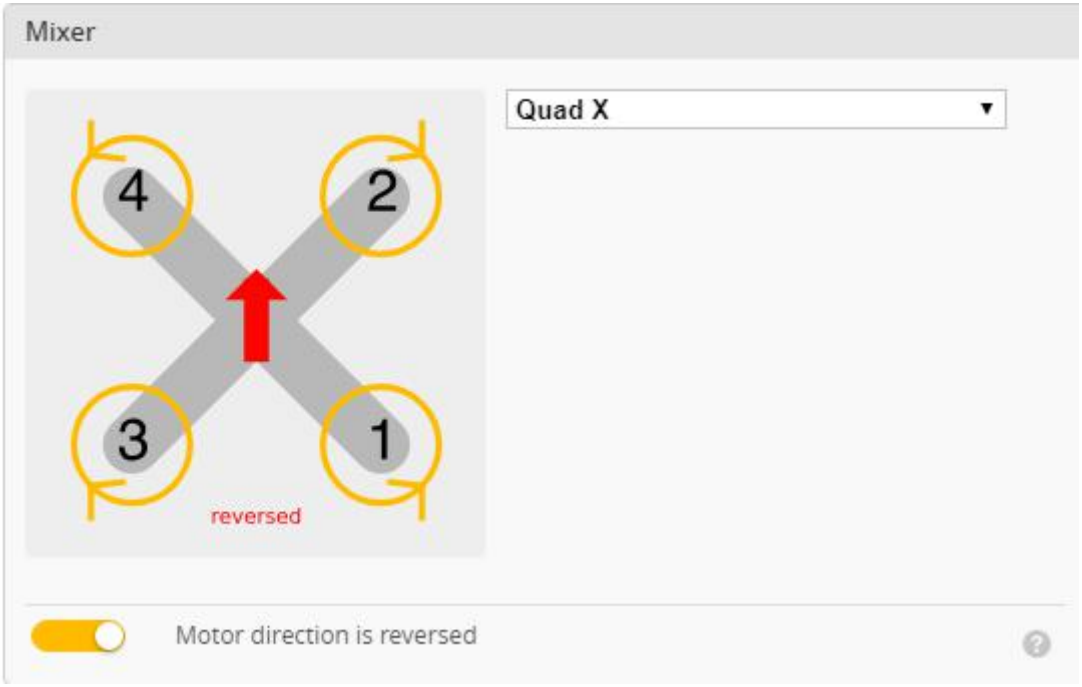

# 5.URAT serial port use

URAT1 uses VTX image transmission

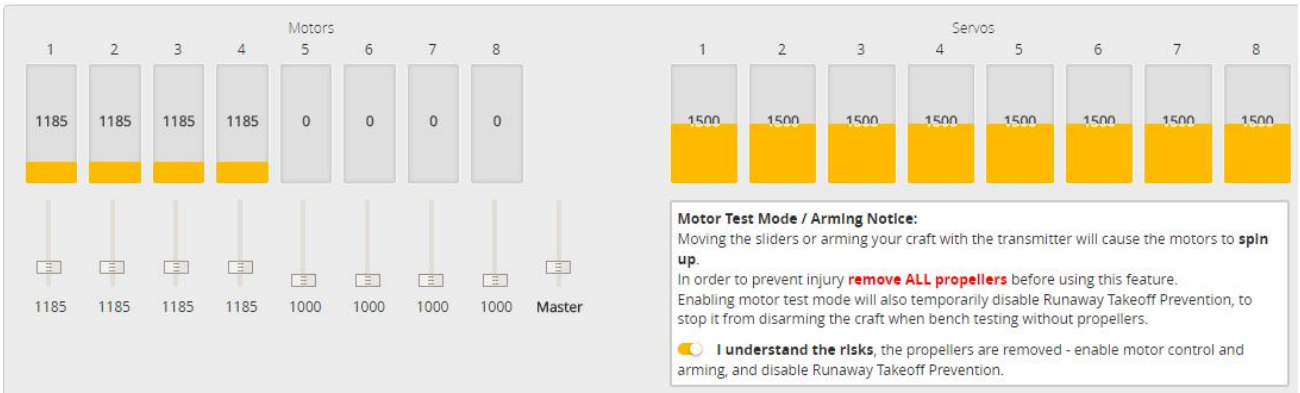
UART2 uses receiver telemetry

# 6.Select aircraft model

1.Click Configuration Select model

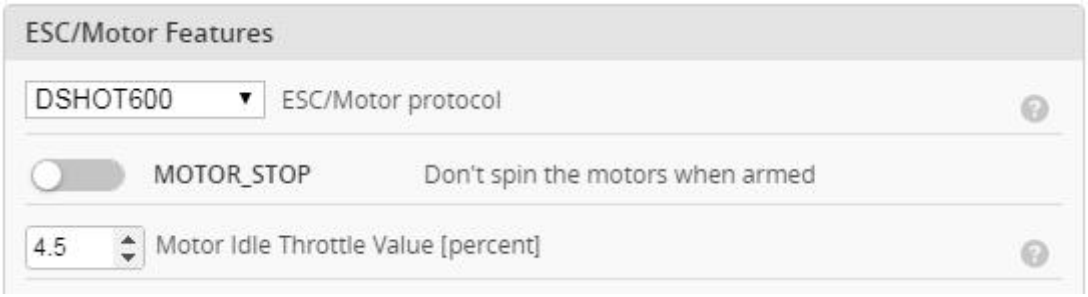



2.Click Motors Click "I understand the risks" Push Master to check motor steering "Master" Steering can be changed at BLHeliSuite



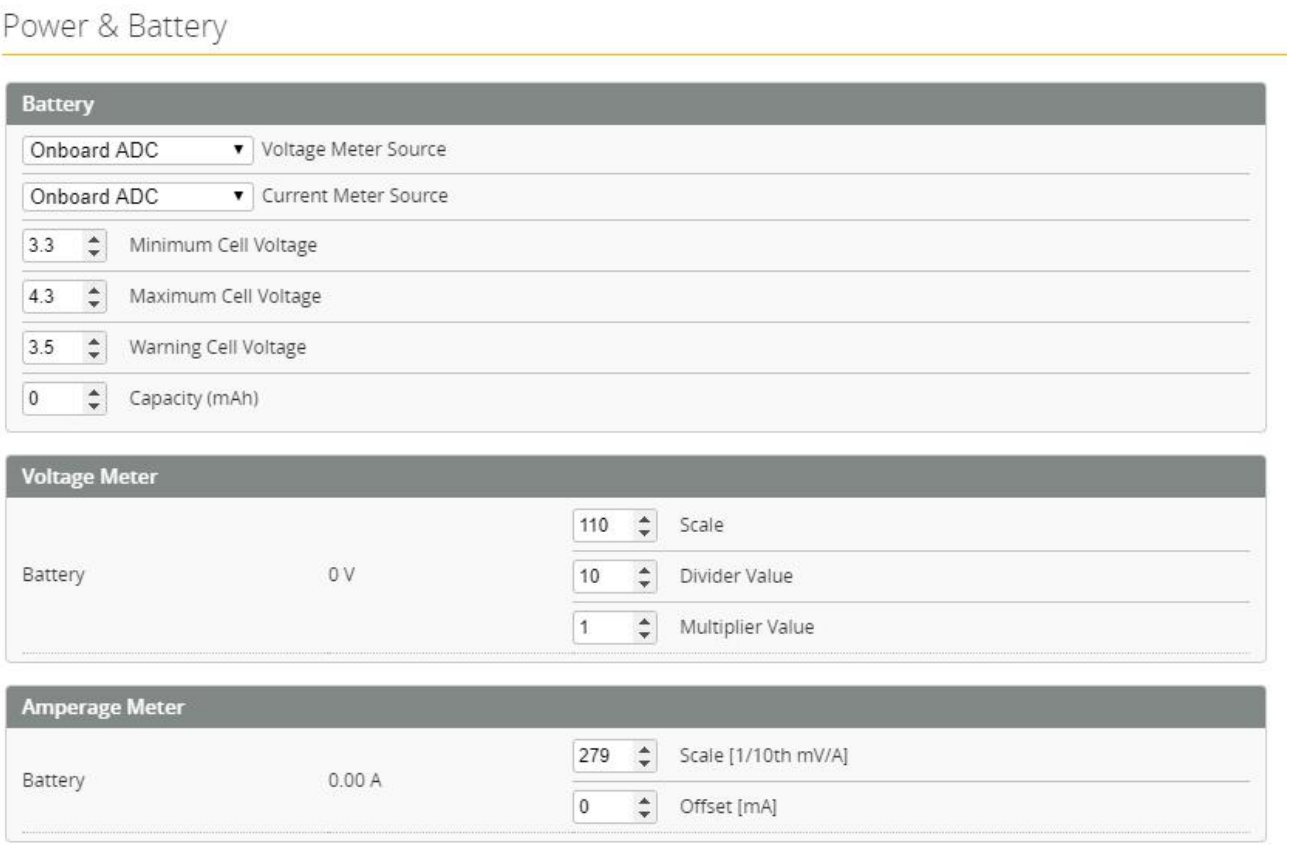
# 7.Choose ESC protocol

1.Choose the right ESC protocol, the optional universal protocol DSHOT600.



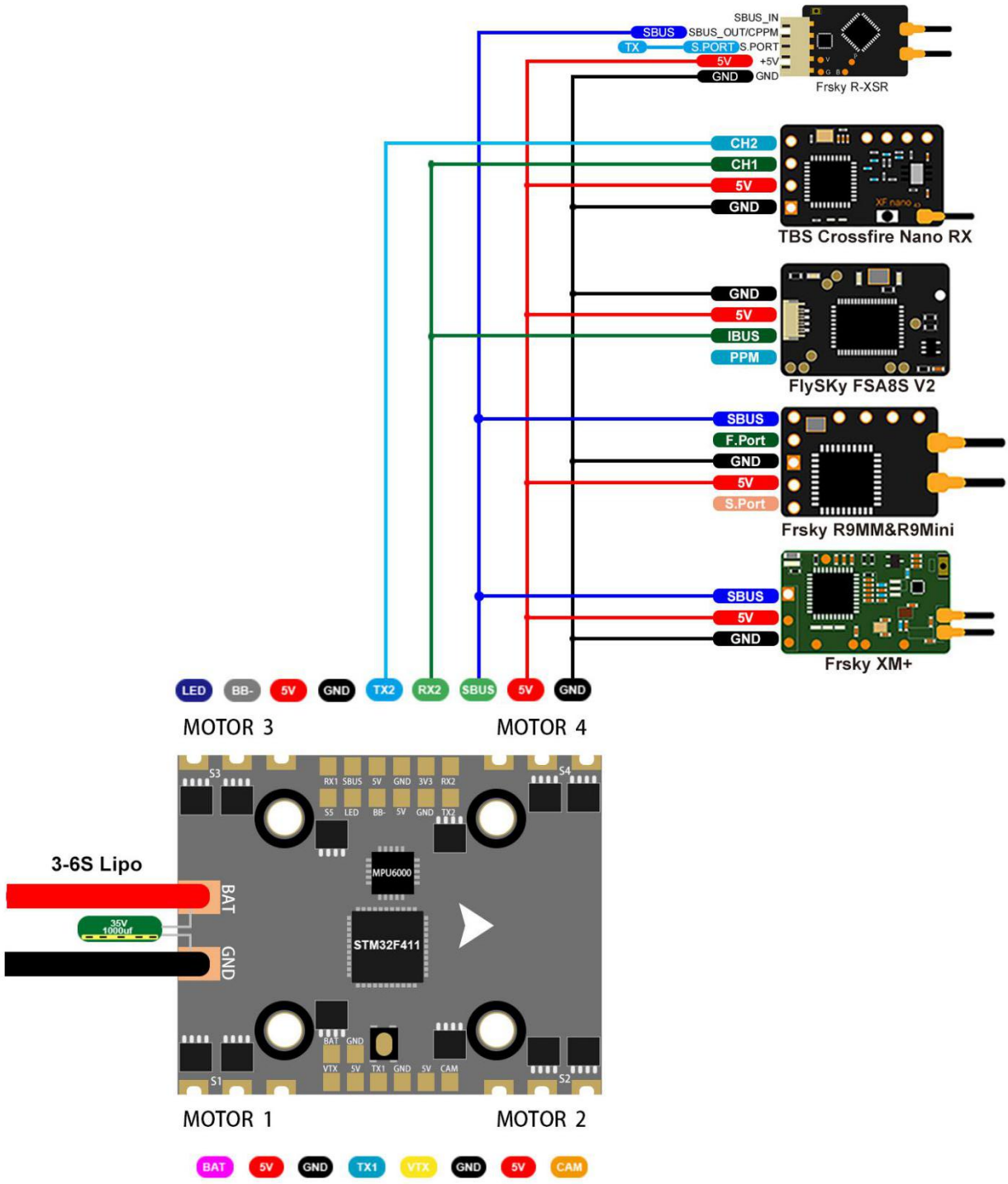

# 8.Voltage parameters setting

1.Click Power & Battery Setting parameters



# 9.Setting up the receiver

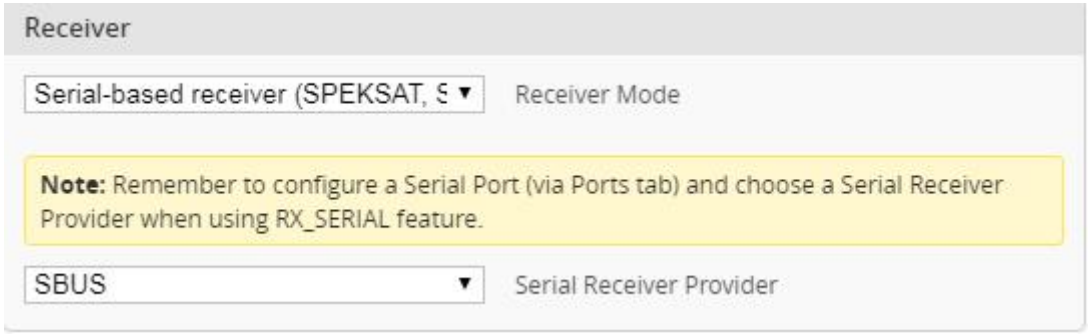
1.Receiver connection diagram



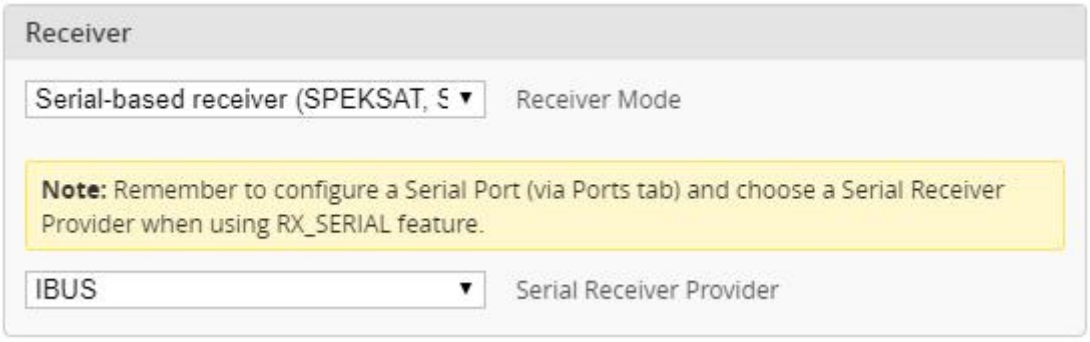
2.Click Ports have found "UART2" Open （SBUS） the receiver serial port


3.Open (i.BUS/DSMX) receiver serial port

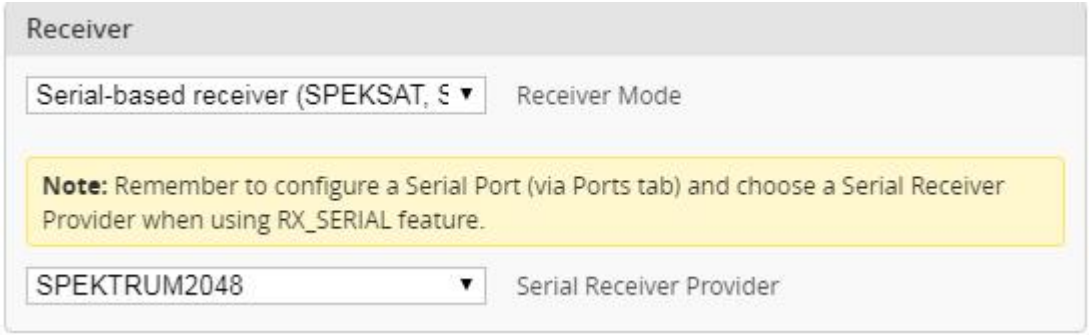

4.Set the SBUS receiver




5.Set the i.BUS receiver

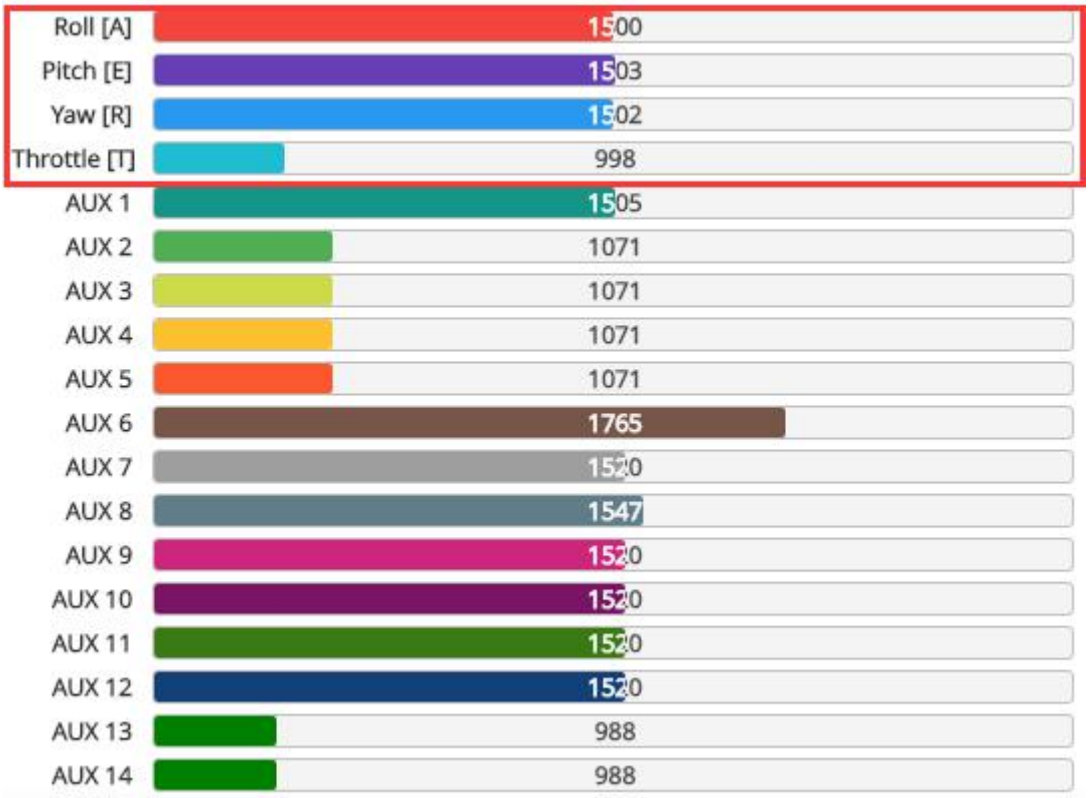



6.Set the DSMX receiver



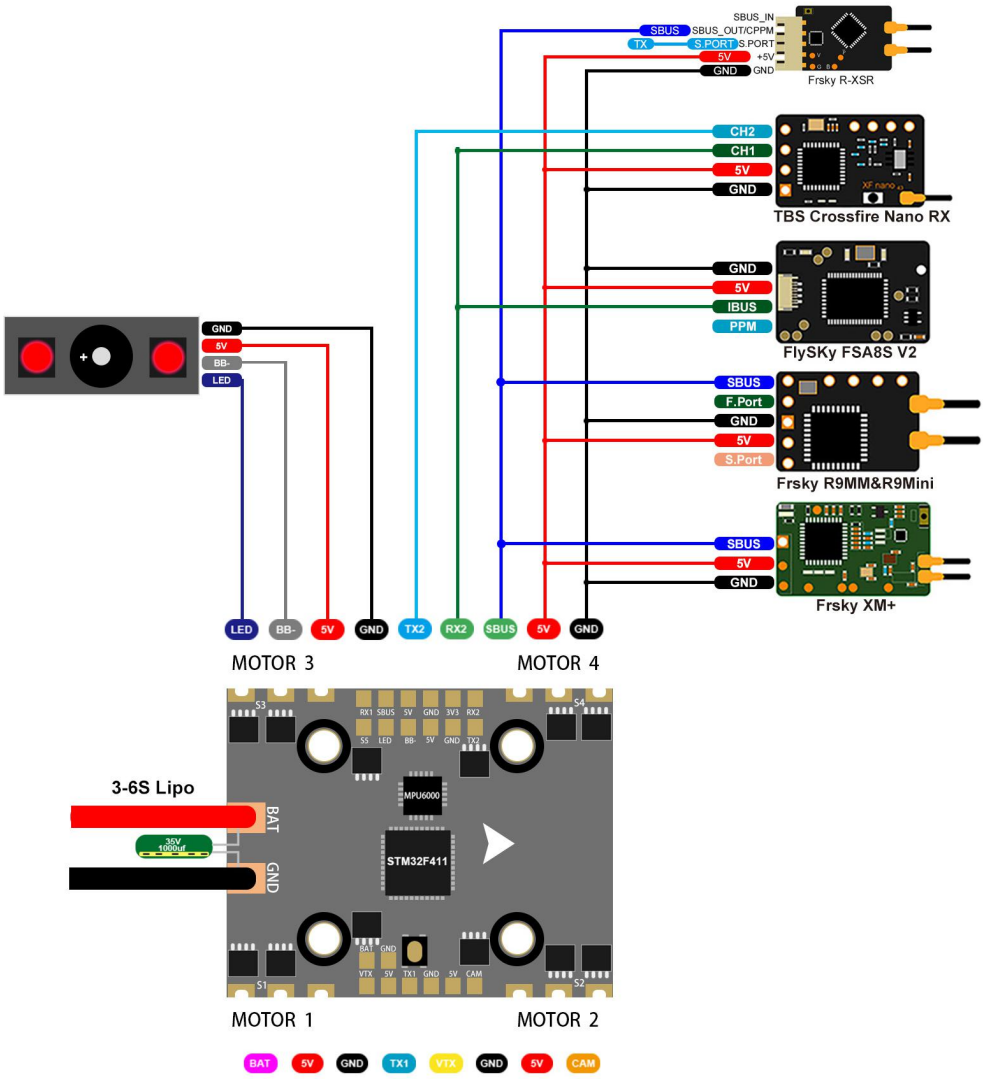
# 10.Check receiver signal

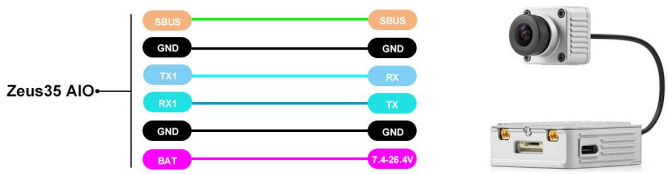
1.Click Receiver Check the remote control output signal



# 11.VTX serial port use. VTX uses OSD smart audio

1.VTX connection diagram

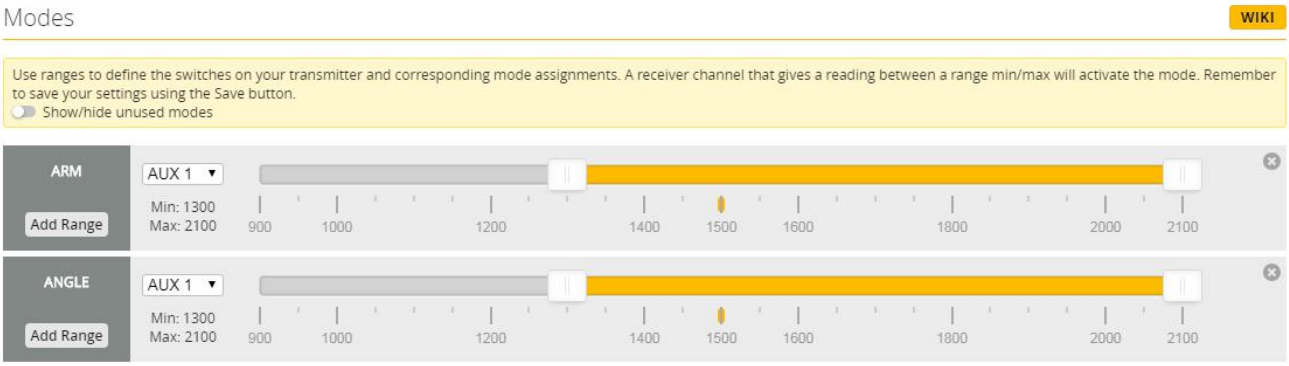


2.VTX serial port opens. The protocol is selected according to its own VTX protocol.


# 12.Select flight mode startup mode

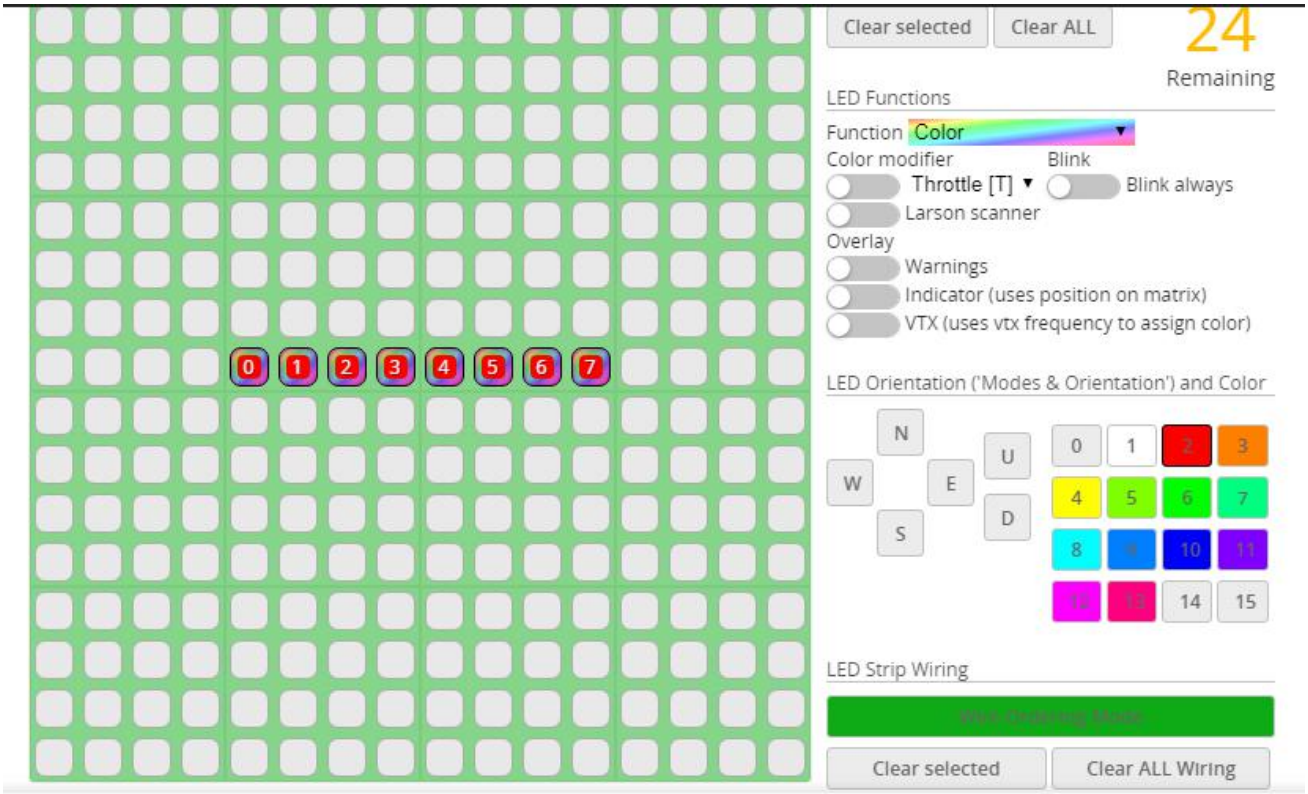
1. Click Modes set up the function of remote control switch across the channel (below are for reference only)



# 13.LED settings

1. Click Configuration Turn on LED support


2.Click LED Strip .Click Wire Ordering Mode set according to need



# 14.Troubleshooting

## Warning:

Please read the cautions as follows, otherwise stability of your flight controller cannot be ensured, your flight controller will even get damaged.

- Keep focus on the polarity. Check carefully before power supply.
- Cut off the power when you connect, plug and pull anything.
- The refresh rate of PID and Gyroscope is up to 8K/8K.

## after sales question:

1. After receiving the goods, it is found that the product can not be used normally. If the return to the factory is a quality problem, the repair service will be provided free of charge.

2. If the product is damaged due to improper operation, the repair service may be provided under the condition that the inspection can be repaired.

3. For domestic customers, please contact the after-sales service personnel. For overseas customers, please contact the official website for after-sales service.

# Product daily problems

## 1. When plugged in the battery, the aircraft does not pass the self-test without "BBB" sound. There is only one sound.

Please check if the ESC agreement is correct

## 2.The spin of the aircraft keeps spinning

1. Please check if the propeller is correct
2. Please check if the motor direction is correct